

Methods for Semantic Mining of Spatio-Temporal Data

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ABSTRACT

Network-based spatio-temporal data has various real-world applications, including financial transactions, transportation, traffic management, and social media analysis. In this context, adequate representation learning is crucial to empower various graph-based downstream applications, including fraud detection, transportation demand prediction, traffic flow estimation and social network interactions. Graph representation learning is not trivial and requires encapsulating spatio-temporal knowledge from the data into a numerical vector, potentially involving a loss of relevant information. Current representation learning for spatio-temporal data typically focuses on implicitly encoding spatio-temporal patterns by leveraging complex architectures. However, such architectures can fail to extract relevant spatio-temporal patterns due to data sparsity or pattern-architectural mismatches. To mitigate the loss of relevant information during representation learning, we propose methods for semantic mining of spatio-temporal data. Semantic mining involves discovering and extracting hidden patterns and explicitly including such patterns in the data to support effective representation learning on graphs.

KEYWORDS

Spatio-temporal data, Semantic mining, Representation learning

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1 INTRODUCTION

Understanding spatio-temporal patterns and interactions is critical for various graph-related activities such as trade with supply chain management [20] or traffic with traffic demand forecasting [16]. Also, with infrastructural growth, data networks become more complex, making spatio-temporal data analysis even more challenging [18]. Moreover, the high cost of data collection reduces the data availability and increases sparsity.

However, state-of-the-art deep learning models employed to analyse spatio-temporal data leverage implicit representation learning mechanisms including complex modules such as graph neural

networks (GNNs) [11], recurrent neural networks (RNNs) [12], convolutional neural networks (CNNs) [8], or their combinations [1]. Yet, these modules have several limitations: First, they require many training samples, which leads to efficiency problems in large networks [10]. Second, they do not explicitly capture data patterns and the implicitly learned interactions, leading to suboptimal results on downstream tasks. Finally, they lack interpretability although demand for interpretable machine learning is rising [19].

In this thesis, we tackle the problem of leveraging semantic mining of spatio-temporal data to augment the data and reduce the loss of key information while performing representation learning. Moreover, semantic mining can enhance the interpretability of deep learning and the methods employed are illustrated in Figure 1. These methods include 1) Correlation extraction, involving the identification of spatio-temporal correlations and incorporation of context information regarding individual graph nodes, and 2) Concept learning, comprising concept definitions based on the domain knowledge and classifiers to align the data points and patterns with the corresponding concepts. Finally, the goal is to empower various downstream applications that can benefit from the results by producing better-performing, more explainable models.

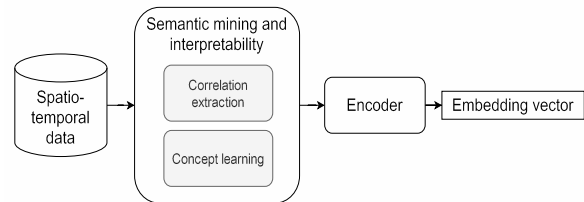


Figure 1: Mining methods

2 DISSERTATION PLAN

There is a need to capture spatio-temporal interactions efficiently in graph-based data and to achieve better interpretability in deep learning, as presented in Section 1. Thus in this thesis, we propose the *semantic mining* approach constructed around two main semantic mining methods for spatio-temporal data: *correlation extraction* and *concept learning*. In this Section, we discuss the motivation and describe the associated problem statements for each method.

2.1 Correlation Extraction

The main motivation is to facilitate more in-depth graph-based data understanding by deep learning methods, providing them with explicit data patterns. Pattern recognition is the principal challenge considering the conjunction of spatial and temporal relationships.

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To address this challenge, we investigate the research question RQ1: *How to leverage spatio-temporal correlation to enhance speed prediction in traffic networks?*, where the focus is summarising the spatio-temporal relationships in the traffic network. Therefore, we leverage a statistical method, mainly the correlation between graph nodes, considering space and time dimensions. Then, the resulting correlation is integrated into traffic speed prediction models.

2.2 Concept Learning

In this semantic mining method, the motivation is to associate prior domain knowledge with deep learning predictive methods. Specifically, we define concepts based on domain knowledge and incorporate classifiers to align the data points and patterns with the corresponding concepts. However, the main challenges here are the high dimensionality of the data and the integration of spatial and temporal features in the concepts.

Thus, we investigate the research question RQ2: *How to learn the patterns that reflect semantic concepts in the data?* The idea is at the earlier stage to define concepts from domain knowledge, and then, learn these concepts by leveraging an appropriate classifier. Considering that this classifier is trained to predict the corresponding concept of each data point, it would allow a flexible inference task in case different models exhibit variable performance depending on the concepts observed in the data. Examples of concepts for the traffic speed prediction task are *rush hour* and *traffic jam (when many cars are delayed in the traffic)*.

2.3 Semantic Mining and Interpretability

After identifying patterns through semantic mining methods, we are interested in interpreting the results of downstream tasks in light of those patterns. The main challenge is the non-linear relation between the results and the data patterns.

Hence, in this phase, we face the research question RQ3: *What impact do patterns in deep learning models have?* Consequently, we develop techniques leveraging spatio-temporal patterns to understand deep learning models better, without damaging the models' performance. This could be done leveraging a mechanism where each pattern discovered in the data has an associated weight learned as the model is optimised. This weight quantifies the impact of the pattern for the overall result [15].

3 PRELIMINARY RESULTS

The preliminary results mainly concern the RQ1 in Section 2.1 and RQ2 in Section 2.2. About RQ1 in correlation extraction, we performed an enrichment mechanism to enhance traffic speed prediction and published the first version of the SCANNER approach [6]. In SCANNER, we demonstrate the importance of enriching the data by leveraging temporal correlation between nodes of the traffic network. Moreover, We are working on a second version of the SCANNER approach comprising a neighbourhood-based data enrichment module (NDE). With the NDE module, the enrichment process also considers the spatial distance between nodes in the traffic network and a longer temporal range for the temporal correlations. The initial results of the second version of the SCANNER approach in Table 1 demonstrate that the NDE module benefits

different model architectures in traffic speed prediction. Specifically, the results present two modalities for each model: without data enrichment (w/o NDE) and with data enrichment (+ NDE), and show the improvement percentage. The dataset used for the experiments is *metr-la* [9], and the metrics are mean absolute error (MAE) and the root-mean-square error (RMSE).

Table 1: Traffic speed models with data enrichment (+ NDE) and without data enrichment (w/o NDE).

| Metrics | Models | w/o NDE | + NDE | Improv. % |
|-------------|--------------|---------|-------|-----------|
| MAE | GRU [3] | 7.46 | 6.96 | 6.69 |
| | STGAT [7] | 4.16 | 3.81 | 8.23 |
| | Wavenet [14] | 3.91 | 3.79 | 3.01 |
| | ST-Norm [4] | 3.53 | 3.35 | 5.29 |
| RMSE | GRU [3] | 12.58 | 12.02 | 4.44 |
| | STGAT [7] | 8.13 | 7.45 | 8.27 |
| | Wavenet [14] | 7.88 | 7.69 | 2.37 |
| | ST-Norm [4] | 7.25 | 6.84 | 5.65 |

Concerning RQ2 in concept learning, we propose an ensemble method for traffic speed prediction. The ensemble approach integrates different models, based on the traffic concepts, to benefit from the diversity of models by making them complementary. This is motivated by the fact that the prediction performance of state-of-the-art approaches for traffic speed prediction might vary with the observed traffic concepts. Concretely, we first define three concepts: 1) reoccurring traffic congestion (RTC), 2) traffic speed transition (TST) and 3) other traffic speed (OTS). Then, we design a deep learning classifier to assign the right concept to each traffic data instance. Our preliminary results in Table 2 confirm the importance of considering concepts, given that the best model (**bold**) as well as the worst model (underline) change depending on the concept.

Table 2: Prediction performance for several traffic-speed concepts using Hanover (Germany) speed data. MAE metric.

| Models / Concepts | OTS | RTC | TST |
|-------------------|-------------|--------------|--------------|
| HA | 4.80 | <u>13.25</u> | 7.39 |
| MA | 3.60 | 4.07 | 6.55 |
| GTS [13] | <u>8.38</u> | 11.89 | <u>16.15</u> |
| G. Wavenet [17] | 2.85 | 4.54 | 14.55 |
| ST-Norm [4] | 2.61 | 4.43 | 13.32 |

4 NEXT STEPS

In the next steps, we will proceed with the concept learning method finalising our proposal for the research question RQ2. In this regard, we are currently investigating systematic concept definitions and a dedicated attention mechanism to weigh the contribution of each model. After that, we plan to complete the architecture and propose a solution for the research question RQ3 following state-of-the-art studies [2, 5]. We want to combine global and local patterns by applying attention layers at different levels of the architecture.

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